New DGFI input data and Combination of techniques at CC DGFI

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New DGFI input data

		VLBI	SLR
	Pole tide	linear mean pole	linear mean pole
eral	A priori EOP	IERS 08 C04	IERS 08 C04
general	A priori EOP interpolation	linear	linear
	Ocean loading	FES2004	FES2004
	Relativistic model	improved	
ique- cific	Satellites		L1/2
technique- specific	Gravity field		EIGEN-GRG.RL02
	Ocean tides		FES2004



Outline

- Input data
- New SINEX files
- Intra-technique combination
- Inter-technique combination



Changes since November 2010

	AIUB	DGFI	ESOC	GFZ	GRGS	MAO	OPA	TUW
GPS	n2				n6			
SLR	n3	w2	w1		n2			
VLBI		n2			n4	n1	n1	n1
DORIS					n5			
L-P			n1	n1				
L-D			n1/n2					

New SINEX files SINEX files Nov. 2010



Seitz: Combination at the CC DGFI

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	AIUB	DGFI	ESOC	GFZ	GRGS	MAO	OPA	TUW
GPS	n2				n6			
SLR	n3	w2	w1		n2			
VLBI		n2			n4	n1	n1	n1
DORIS					n5			
L-P			n1	n1				
L-D			n1/n2					

New SINEX files SINEX files Nov. 2010



Input data

Remarks to the new SINEX files

- GPSGRGS: orientation constrained (n6/n7)AIUB: many DOMES numbers are used twice
- **SLR** AIUB, DGFI, GRGS: okay
- VLBI DGFI, MAO, OPA, TUW: okay
 - GRGS: station names are not given for all of the troposphere parameters
- **DORIS** "D" in SINEX file is shifted by one column (SATA_*)

→ Except of [GPS/GRGS] all NEQ provide the expected number of degrees of freedom



Analysis and combination procedure at DGFI

Step by step

Per technique:

- daily to weekly [GPS/AIUB]
- comparison and combination of input files

Inter-technique1:

- comparison and combination of VLBI-, SLR-, and GPS-only contributions

Inter-technique2:

 comparison and combination of intertechnique 1 and pre-combined SLR-DORIS, SLR-GPS data



Contributions: DGFI, MAO, OPA, TUW (GRGS could not be read from SINEX)

Analysis:

	A posteriori Sigma	Transformation DTRF2008 (scale)	RMS of transformation
DGFI	1.0	<= 9 mm	5 – 7 mm
MAO	20.0	20-30 mm	20-30 mm
OPA	800000.0	<= 10 mm	5 – 7 mm
TUW	1.0	<= 10 mm	5 – 7 mm

- \rightarrow DGFI, OPA and TUW are combined.
- → standard deviations of OPA very large (Itpl of 1*10^15 vs. 1*10^4 for DGFI and TUW) → contribution to combined solution is very small



Combination aspects

- Consideration of variance components is necessary
- DGFI, OPA: EOP transformed from O+D -> pwl
- Troposphere parameters (TUW): have to be stabilized
- Sources (TUW): fixed to ICRF2
- dUT1: DGFI and TUW (UT1-UTC); OPA (UT1-TAI)

 > dUT1 combined for DGFI and TUW only

 Nutation: TUW[X,Y]; DGFI and OPA [PSI, EPS]

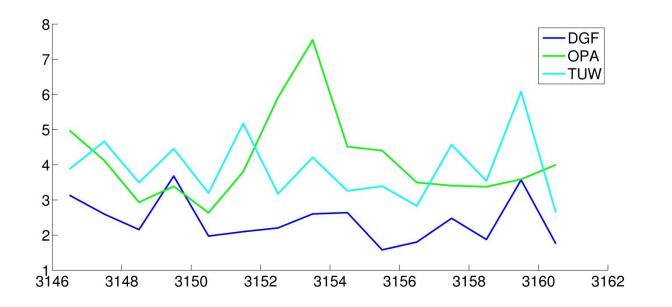
 OPA: a priori values are not 0.0 (model values?)
 > nutation is not combined

 \rightarrow Parameterization of VLBI contributions must be further homogenized.



Combination results

RMS of similarity transformation between combined and single AC solutions

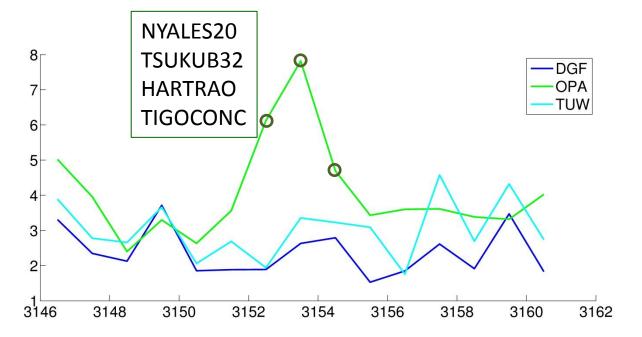


\rightarrow Offsets between the AC contributions



Combination results

RMS of similarity transformation between combined and single AC solutions

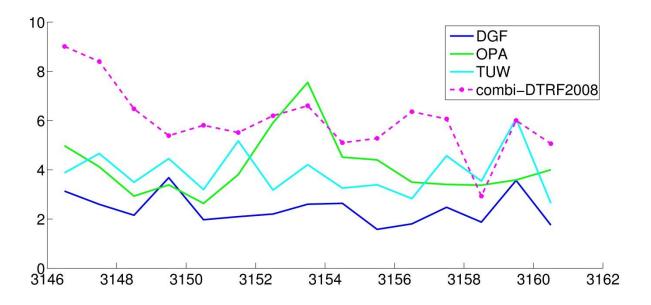


 \rightarrow NYALES20 not used in transformation: offset between DGF and TUW removed. What are the reasons? Modell differences? (\rightarrow height component)



Combination results

RMS of similarity transformation between combined and single AC solutions



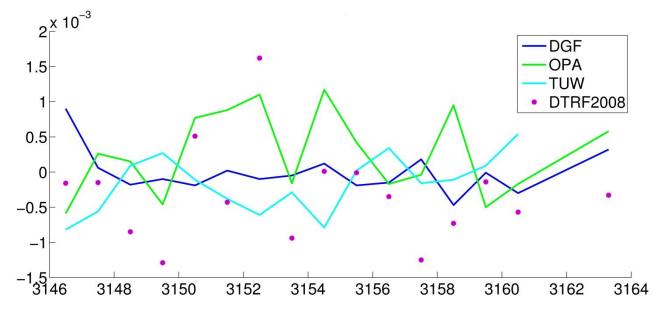
→ Agreement of AC better than agreement to DTRF2008 (model differences; epoch vs. multi-year solution)



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Combination results

Scale differences [ppm] derived from transformation between combined and single AC solutions (and DTRF2008)

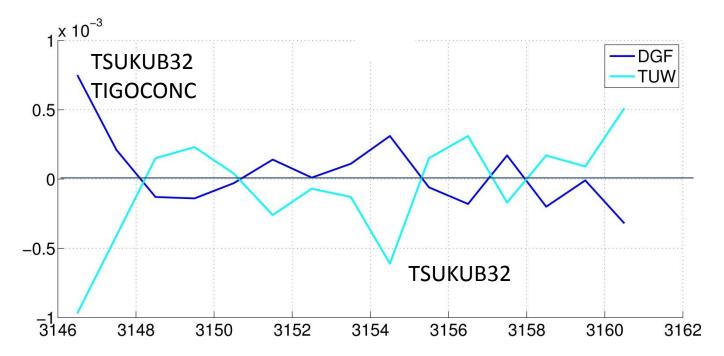


- \rightarrow Contribution of OPA very small (due to large STD).
- → RMS of scale differences between AC comparable to comparison of combined solution and DTRF2008 (Offset: -0.5 ppb)



Combination results

Scale differences [ppm] derived from transformation between combined and single AC solutions



\rightarrow Scale is weighted mean of DGF and TUW.



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Summary:

- Good agreement (MAO should be analyzed in detail)
- EOP parameterization must be homogenized (Nutation, dUT1)
 - DGF, MAO and OPA -> [X,Y]
 - Nutation parameters: correction to nutation model a priori values = 0.0
 - OPA -> UT1-UTC
 - Same a priori values, interpolation
- SINEX completed (GRGS)
- Standard deviations of OPA must be investigated
- What are the reasons for the disagreements between the ACs?



Contributions: AIUB, DGFI, GRGS

Analysis:

	A posteriori Sigma	Transformation DTRF2008 (tra, sc)	RMS of transformation
AIUB	0.01	<= 5 mm	15 mm
DGFI	1.3	<= 10 mm	15 mm
GRGS	0.5	<= 10 mm	15 mm

- ightarrow Homogeneous SLR input data
- \rightarrow Second week slightly worse than weeks 1 and 3



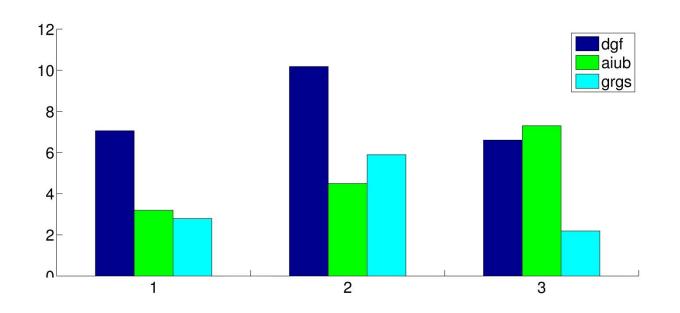
Combination aspects

- Consideration of variance components is necessary
- Geocentre coordinates (AIUB) fixed to 0.0
- EOP:
 - CODE: O+D -> pwl
 - GRGS provides pwl values at noon (cannot be transformed)
 - -> only the EOP of AIUB and DGFI are combined
 - week 3 cannot be solved if EOP are combined (ITPI) !!
 What is the reason?



Combination results

RMS [mm] of similarity transformation between combined and single AC solutions

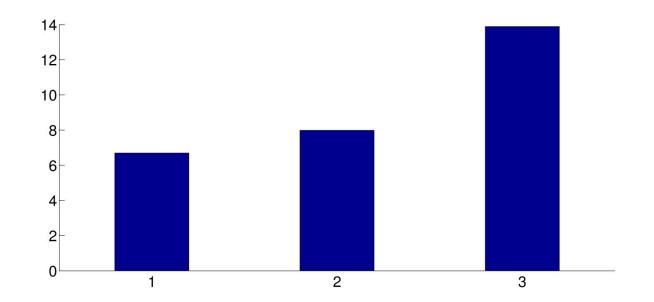


→ Comparable RMS values, DGFI values (weeks 1 and 2) slightly larger (improved compared to first DGFI solution)



Combination results

RMS of similarity transformation between combined solution and DTRF2008

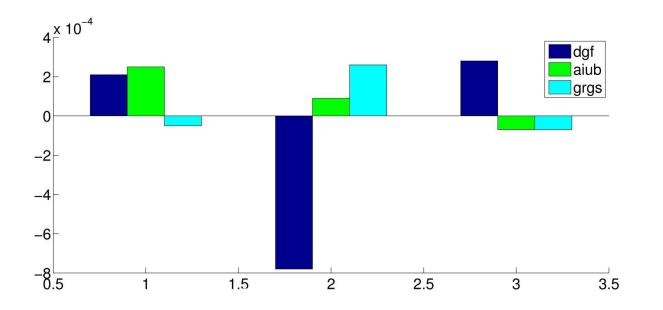


→ Comparable to RMS for single AC w.r.t. DTRF2008 (15 mm); week 1 and 2 benefit from combination



Combination results

Scale differences [ppm] between combined solution and single AC solutions

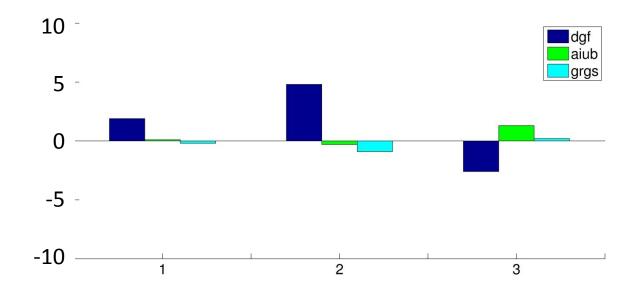


→ Agreement: 0.2 ppb (~ 1.5 mm) ; except of week 2 / DGFI



Combination results

X-Translations [mm] between combined solution and singe AC solutions

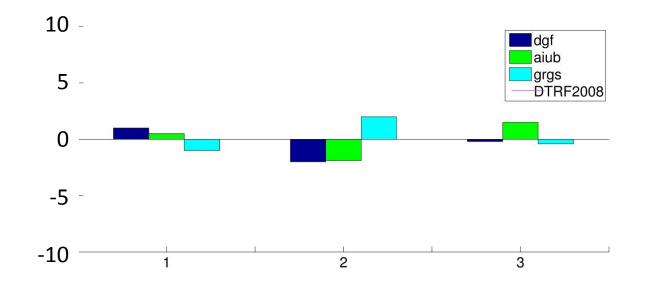


 \rightarrow Agreement within 5.0 mm



Combination results

Y-Translations [mm] between combined solution and singe AC solutions

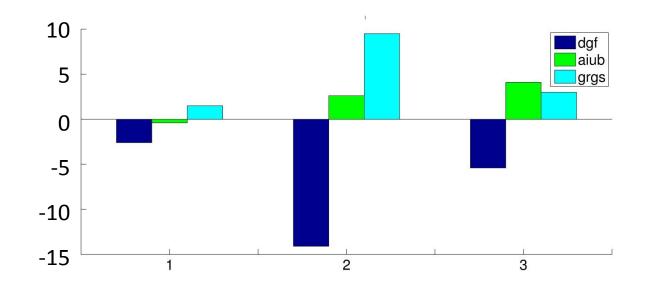


 \rightarrow Agreement within 2.0 mm



Combination results

Z-Translations [mm] between combined solution and singe AC solutions

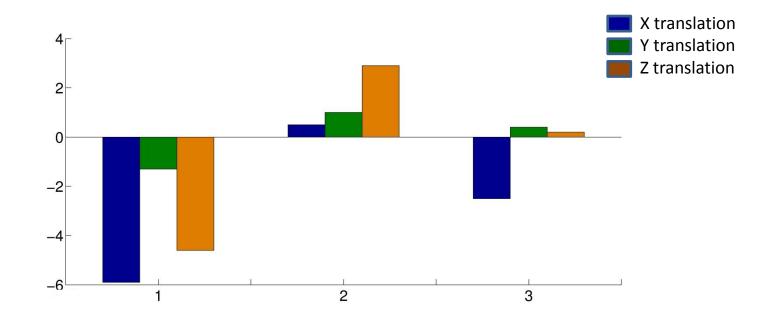


→ Agreement within 5.0 mm for week 1 and 3
→ Summarizing: homogeneous SLR input data



Combination results

Translations of combined solution w.r.t. DTRF2008 [mm]

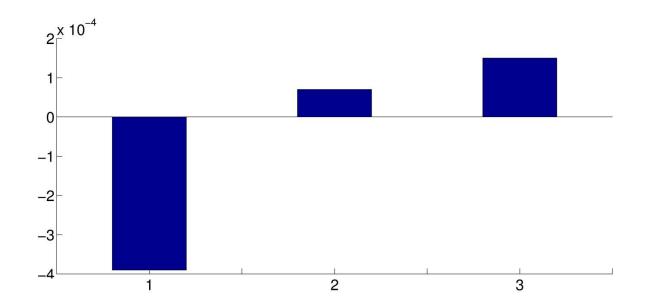


\rightarrow Agreement within 6 mm.



Combination results

Scale of combined solution w.r.t. DTRF2008 [ppm]



→ Agreement: 0.4 ppb (~ 2.5 mm)



Contributions: AIUB, GRGS

Analysis:

	A posteriori Sigma	Transformation DTRF2008	RMS of transformation
AIUB	0.01	datum parameters set up	7.0 mm
GRGS	2.0	datum parameters set up	6.0 mm

Combination:

RMS values (combined / single AC): 2-5 mm

RMS w.r.t. DTRF2008: 4-5 mm (Improvement compared to single AC)

 \rightarrow Good agreement



Contributions: GRGS

Analysis:

	A posteriori Sigma		RMS of transformation
GRGS	1.0	datum parameters set up	10-20 mm

Combination:

 \rightarrow No intra-technique combination for DORIS



Inter-technique combination

Flowchart of weekly combination

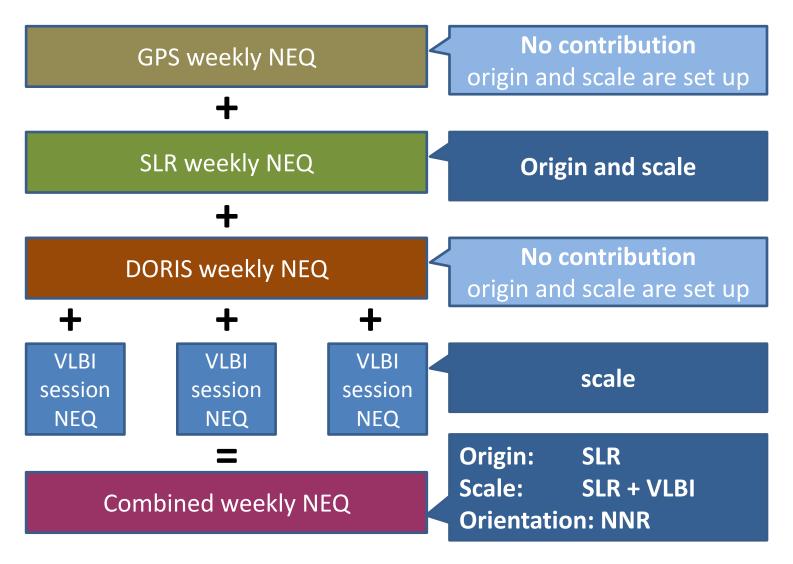
GPS weekly NEQ ╋ SLR weekly NEQ **DORIS** weekly NEQ ╋ ╇ ╇ **VLBI VLBI VLBI** session session session NEQ NEQ NEQ Combined weekly NEQ

Selection of local ties Max. local tie misfit : 25 mm

σ local ties 1.0 mm / component



Combination: Datum realization

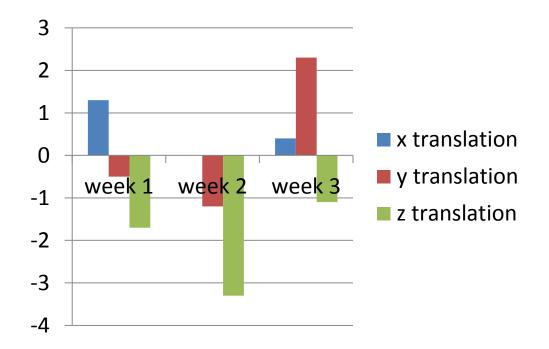




Combination: Datum realization

Conservation of the origin

Translation between combined (P+R+L+D) and SLR only [mm]



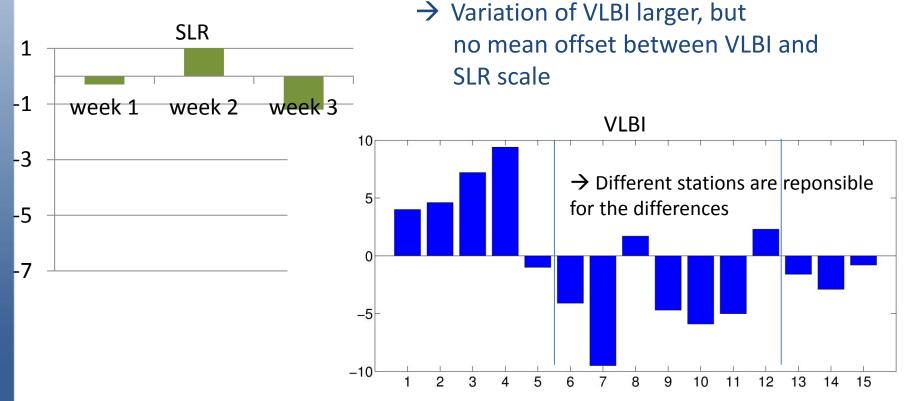
 \rightarrow Good agreement between SLR only and combined solution



Combination: Datum realization

Conservation of the scale

Scale parameters between combined and VLBI/SLR only [mm]

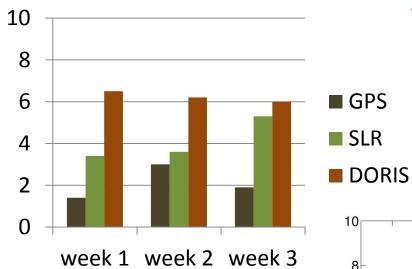




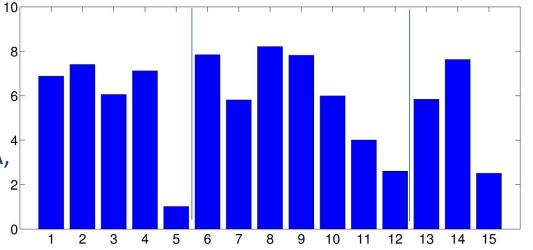
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Combination: deformation of networks

RMS values of transformation between combined and single technique solution



VLBI stations with frequent residuals of 10-20 mm: NYALES20, SVETLOE, TSUKUBA, KOKEE, WESTFORD → Mean deformation can reach more than 5mm
 SLR: Asian stations responsible for large RMS



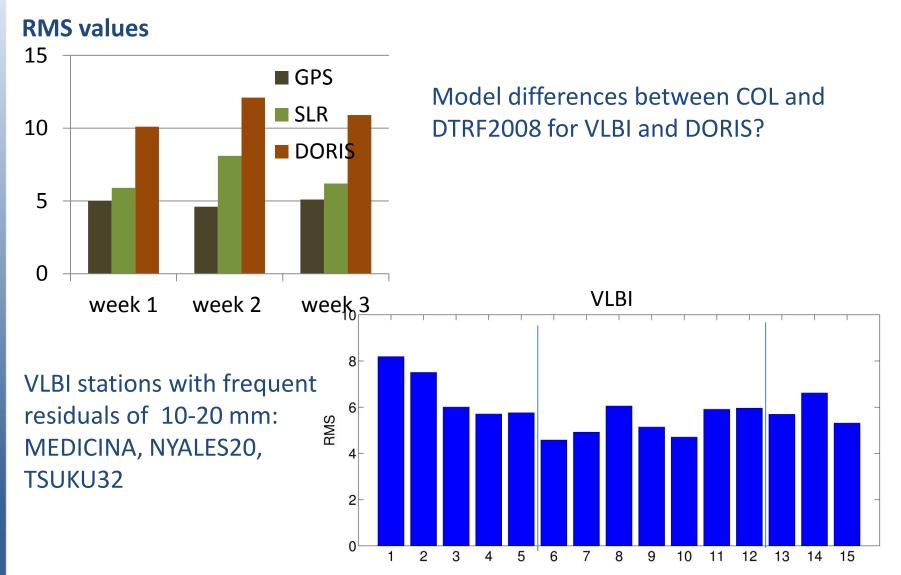


Combination: Comparison with DTRF2008

Translations SLR , GPS: VLBI, DORIS:	-6.0 – 3.5 mm -10.0 –6.0 mm, 5.0	0 – 10.0 mm
Rotations		
GPS:	-0.4 – 1.5 mm	Datum realization w.r.t. DTRF2008
SLR:	-6.0 – 1.8 mm	~ 5mm per component
VLBI:	-9.0 – 7.0 mm	(GPS orientation better)
DORIS:	-11.0 – 11.0 mm	
Scale VLBI:	-4.0 – 5.0 mm	 Transfer into network parts translation/rotation : up to 11 mm Scale: up to ~ 5 mm
SLR:	-2.3 – 1.4 mm	
GPS:	-1.6 – -2.5 mm	
DORIS:	-3.7 – -5.3 mm	



Combination: Comparison with DTRF2008







Combination: EOP

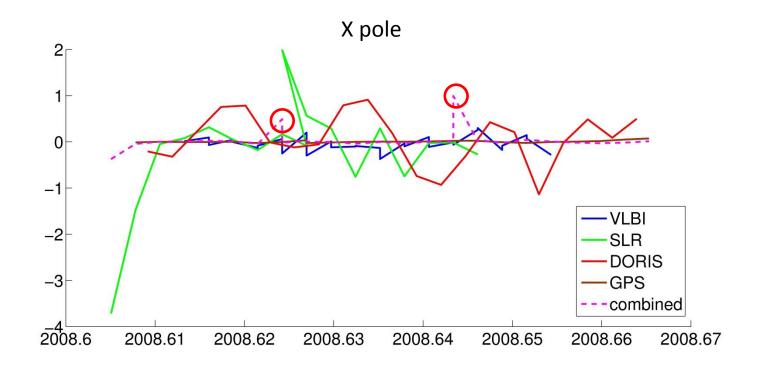
Combination of EOP (piece-wise linear at 0 h)

	pole	UT1-UTC	Nutation
GPS	AIUB+GRGS	AIUB (GRGS: UT1-TAI)	AIUB (GRGS: AV≠0)
SLR	AIUB (GRGS: pwl 12 h)	AIUB (GRGS: UT1-TAI; pwl 12 h)	/
VLBI	DGFI+GRGS+ TUW	DGFI+TUW (GRGS: UT1-TAI)	DGFI: mean epoch, no rates GRGS: AV≠0, mean epoch, no rates TUW: X,Y
DORIS	GRGS	/ (GRGS: UT1-TAI)	/ (GRGS: AV≠0)
Combined ?	yes	yes	no



Seitz: Combination at the CC DGFI

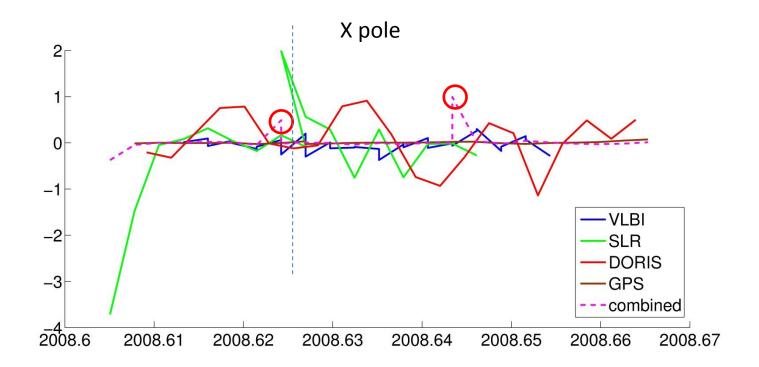
Pole coordinates (w.r.t. IERS 08 C04)



SLR week 3 cannot be solved



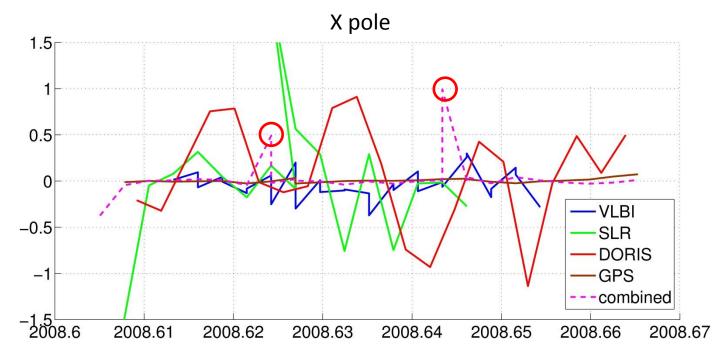
Pole coordinates (w.r.t. IERS 08 C04)



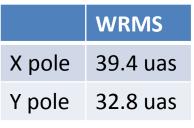
SLR week 3 cannot be solved



Pole coordinates (w.r.t. IERS 08 C04)

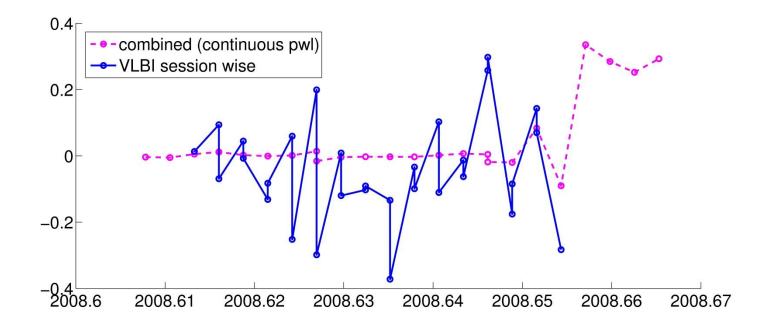


 → Outliers due to SLR contribution (AIUB values: transformation from O+D -> pwl ?)
 → Y pole shows the same effects





UT1-UTC (w.r.t. IERS 08 C04)



	WRMS
UT1-UTC	20.1 us (w/o last four values)



Seitz: Combination at the CC DGFI

Summary: to do

Input data

Correct SINEX file:

constraints, statistical information, station names (tropospheric parameters), source names, satellite names

Parameterization:

IERS2010 should be used (what about the new pole representation in the pole tide model?), Nutation -> [X,Y], UT1-UTC, same a priori values, for EOP: pwl at 0h or O+D

Combination

- Combination of all parameters
- Investigation of individual co-location sites
- VCE
- Pre-combined data should be included (more discussion is needed)

